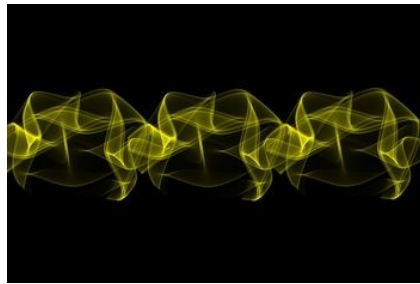


Introduction to Electromagnetic Theory

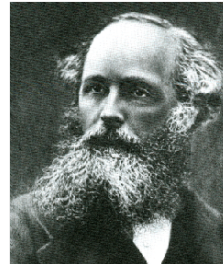
Lecture topics

- Laws of magnetism and electricity
- Meaning of Maxwell's equations
- Solution of Maxwell's equations

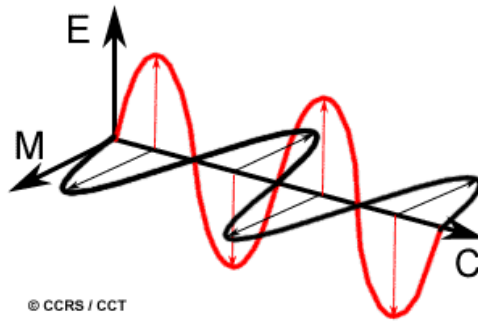


Electromagnetic radiation: wave model

- James Clerk Maxwell (1831-1879) – Scottish mathematician and physicist
- Wave model of EM energy
 - Unified existing laws of electricity and magnetism (Newton, Faraday, Kelvin, Ampère)
 - Oscillating electric field produces a magnetic field (and vice versa) – propagates an EM wave
 - Can be described by 4 differential equations
 - Derived speed of EM wave in a vacuum

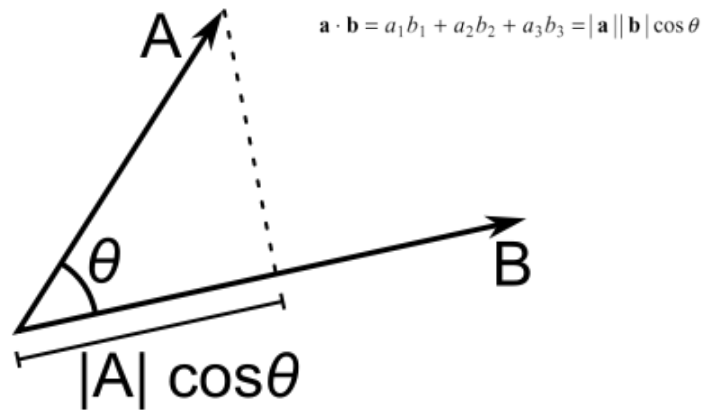


Electromagnetic radiation



- EM wave is:
- Electric field (E) perpendicular to magnetic field (M)
- Travels at velocity, c ($3 \times 10^8 \text{ ms}^{-1}$, in a vacuum)

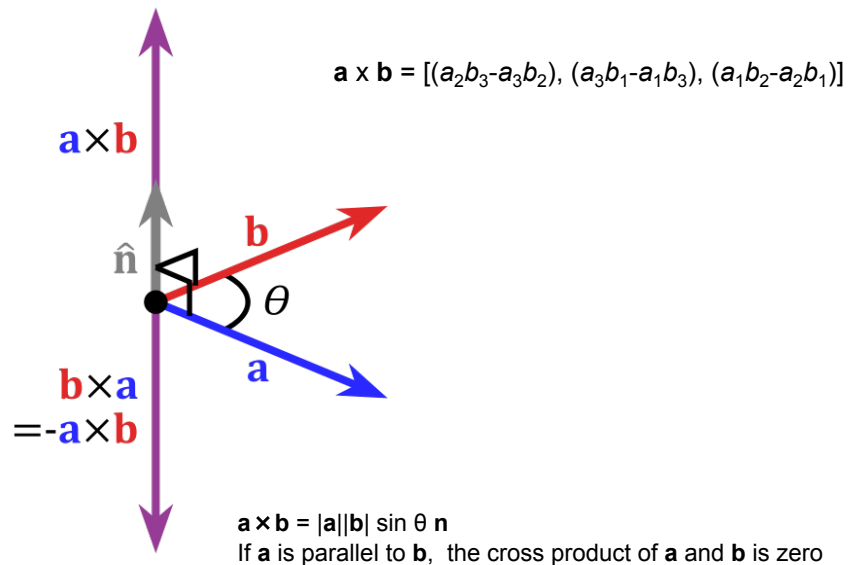
Dot (scalar) product



$$\mathbf{A} \cdot \mathbf{B} = |\mathbf{A}||\mathbf{B}| \cos \theta$$

If \mathbf{A} is perpendicular to \mathbf{B} , the dot product of \mathbf{A} and \mathbf{B} is zero

Cross (vector) product



Div, Grad, Curl

Types of 3D **vector derivatives**:

The **Del** operator:

$$\bar{\nabla} \equiv \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right)$$

The **Gradient** of a scalar function f (vector):

$$\bar{\nabla} f \equiv \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right)$$

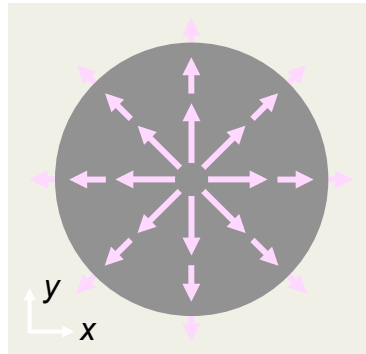
Div, Grad, Curl

The **Divergence** of a vector function (scalar):

$$\nabla \cdot \vec{f} = \frac{\partial f_x}{\partial x} + \frac{\partial f_y}{\partial y} + \frac{\partial f_z}{\partial z}$$

The **Divergence** is nonzero if there are sources or sinks.

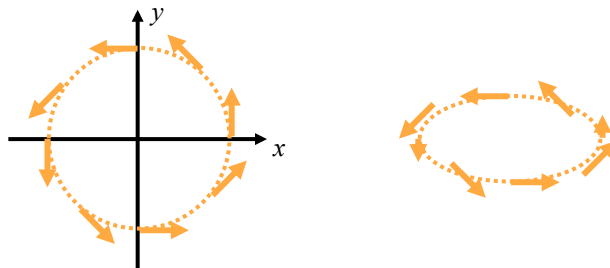
A 2D source with a large divergence:



Div, Grad, Curl

The **Curl** of a vector function \vec{f} :

$$\vec{\nabla} \times \vec{f} \equiv \left(\frac{\partial f_z}{\partial y} - \frac{\partial f_y}{\partial z}, \frac{\partial f_x}{\partial z} - \frac{\partial f_z}{\partial x}, \frac{\partial f_y}{\partial x} - \frac{\partial f_x}{\partial y} \right)$$



Functions that tend to **curl around** have large curls.

http://mathinsight.org/curl_idea

Div, Grad, Curl

The **Laplacian** of a scalar function :

$$\begin{aligned}\nabla^2 f &\equiv \vec{\nabla} \cdot \vec{\nabla} f = \vec{\nabla} \cdot \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right) \\ &= \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}\end{aligned}$$

The **Laplacian of a vector** function is the same, but for each component of f :

$$\nabla^2 \vec{f} = \left(\frac{\partial^2 f_x}{\partial x^2} + \frac{\partial^2 f_x}{\partial y^2} + \frac{\partial^2 f_x}{\partial z^2}, \frac{\partial^2 f_y}{\partial x^2} + \frac{\partial^2 f_y}{\partial y^2} + \frac{\partial^2 f_y}{\partial z^2}, \frac{\partial^2 f_z}{\partial x^2} + \frac{\partial^2 f_z}{\partial y^2} + \frac{\partial^2 f_z}{\partial z^2} \right)$$

The Laplacian tells us the curvature of a vector function.

Maxwell's Equations

- Four equations relating electric (**E**) and magnetic fields (**B**) – vector fields
- ϵ_0 is **electric permittivity of free space** (or vacuum permittivity - a constant) – *resistance to formation of an electric field in a vacuum*
- $\epsilon_0 = 8.854188 \times 10^{-12}$ Farad m^{-1}
- μ_0 is **magnetic permeability of free space** (or magnetic constant - a constant) – *resistance to formation of a magnetic field in a vacuum*
- $\mu_0 = 1.2566 \times 10^{-6}$ T.m/A (T = Tesla; SI unit of magnetic field)

$$\nabla \cdot E = \frac{\rho}{\epsilon_0}$$

$$\nabla \cdot B = 0$$

$$\nabla \times E = -\frac{\partial B}{\partial t}$$

$$\nabla \times B = \mu_0 J + \epsilon_0 \mu_0 \frac{\partial E}{\partial t}$$

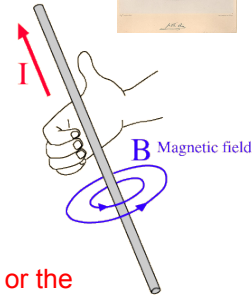
Note: $\nabla \cdot$ is 'divergence' operator and $\nabla \times$ is 'curl' operator

Biot-Savart Law (1820)



- Jean-Baptiste Biot and Felix Savart (French physicist and chemist)
- The magnetic field \mathbf{B} at a point a distance \mathbf{R} from an infinitely long wire carrying current I has magnitude:

$$B = \frac{\mu_0 I}{2\pi R}$$



- Where μ_0 is the **magnetic permeability of free space or the magnetic constant**
- Constant of proportionality linking magnetic field and distance from a current
- Magnetic field strength decreases with distance from the wire
- $\mu_0 = 1.2566 \times 10^{-6} \text{ T}\cdot\text{m/A}$ (T = Tesla; SI unit of magnetic field)

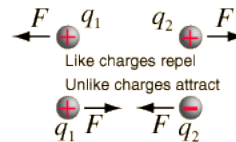
Coulomb's Law (1783)



- Charles Augustin de Coulomb (French physicist)
- The magnitude of the electrostatic force (F) between two point electric charges (q_1, q_2) is given by:

$$F = \frac{q_1 q_2}{4\pi\epsilon_0 r^2}$$

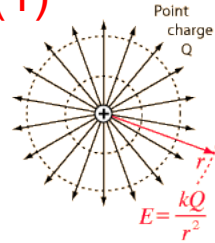
- Where ϵ_0 is the **electric permittivity or electric constant**
- Like charges repel, opposite charges attract
- $\epsilon_0 = 8.854188 \times 10^{-12} \text{ Farad m}^{-1}$





Maxwell's Equations (1)

$$\nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon_0}$$

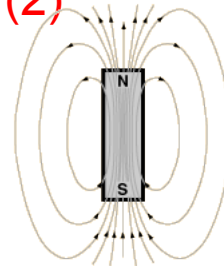


- **Gauss' law for electricity:** the electric flux out of any closed surface is proportional to the total charge enclosed within the surface; i.e. a charge will radiate a measurable field of influence around it.
- \mathbf{E} = electric field, ρ = net charge inside, ϵ_0 = vacuum permittivity (constant)
- Recall: divergence of a vector field is a measure of its tendency to converge on or repel from a point.
- Direction of an electric field is the direction of the force it would exert on a positive charge placed in the field
- If a region of space has more electrons than protons, the total charge is negative, and the direction of the electric field is negative (inwards), and vice versa.

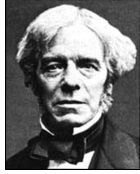


Maxwell's Equations (2)

$$\nabla \cdot \mathbf{B} = 0$$

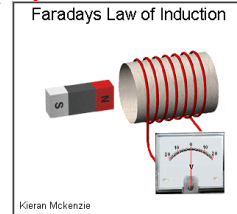


- **Gauss' law for magnetism:** the net magnetic flux out of any closed surface is zero (i.e. magnetic monopoles do not exist)
- \mathbf{B} = magnetic field; magnetic flux = $\mathbf{B}A$ (A = area perpendicular to field \mathbf{B})
- Recall: divergence of a vector field is a measure of its tendency to converge on or repel from a point.
- Magnetic sources are dipole sources and magnetic field lines are loops – we cannot isolate N or S 'monopoles' (unlike electric sources or point charges – protons, electrons)
- Magnetic monopoles *could* exist, but have never been observed



Maxwell's Equations (3)

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$



- **Faraday's Law of Induction:** the curl of the electric field (\mathbf{E}) is equal to the negative of rate of change of the magnetic flux through the area enclosed by the loop
- \mathbf{E} = electric field; \mathbf{B} = magnetic field
- Recall: curl of a vector field is a vector with magnitude equal to the maximum 'circulation' at each point and oriented perpendicularly to this plane of circulation for each point.
- Magnetic field weakens \rightarrow curl of electric field is positive and vice versa
- Hence changing magnetic fields affect the curl ('circulation') of the electric field – basis of electric generators (moving magnet induces current in a conducting loop)



Maxwell's Equations (4)

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{J} + \epsilon_0 \mu_0 \frac{\partial \mathbf{E}}{\partial t}$$

- **Ampère's Law:** the curl of the magnetic field (\mathbf{B}) is proportional to the electric current flowing through the loop
AND to the rate of change of the electric field. \leftarrow added by Maxwell
- \mathbf{B} = magnetic field; \mathbf{J} = current density (current per unit area); \mathbf{E} = electric field
- The curl of a magnetic field is basically a measure of its strength
- First term on RHS: in the presence of an electric current (\mathbf{J}), there is always a magnetic field around it; \mathbf{B} is dependent on \mathbf{J} (e.g., *electromagnets*)
- Second term on RHS: a changing electric field generates a magnetic field.
- Therefore, generation of a magnetic field does not require electric current, only a changing electric field. An oscillating electric field produces a variable magnetic field (as dE/dT changes)

Putting it all together....

- An oscillating electric field produces a variable magnetic field. A changing magnetic field produces an electric field....and so on.
- In 'free space' (vacuum) we can assume current density (J) and charge (ρ) are zero i.e. there are no electric currents or charges
- Equations become:

$$\nabla \cdot \vec{E} = 0$$

$$\nabla \cdot \vec{B} = 0$$

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\nabla \times \vec{B} = \epsilon_0 \mu_0 \frac{\partial \vec{E}}{\partial t}$$

Solving Maxwell's Equations

Take curl of:

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\vec{\nabla} \times [\vec{\nabla} \times \vec{E}] = \vec{\nabla} \times \left[-\frac{\partial \vec{B}}{\partial t}\right]$$

Change the order of differentiation on the RHS:

$$\vec{\nabla} \times [\vec{\nabla} \times \vec{E}] = -\frac{\partial}{\partial t} [\vec{\nabla} \times \vec{B}]$$

Solving Maxwell's Equations (cont'd)

But (Equation 4):

$$\vec{\nabla} \times \vec{B} = \mu\epsilon \frac{\partial \vec{E}}{\partial t}$$

Substituting for $\vec{\nabla} \times \vec{B}$, we have:

$$\vec{\nabla} \times [\vec{\nabla} \times \vec{E}] = -\frac{\partial}{\partial t} [\vec{\nabla} \times \vec{B}] \Rightarrow \vec{\nabla} \times [\vec{\nabla} \times \vec{E}] = -\frac{\partial}{\partial t} \left[\mu\epsilon \frac{\partial \vec{E}}{\partial t} \right]$$

Or:

$$\vec{\nabla} \times [\vec{\nabla} \times \vec{E}] = -\mu\epsilon \frac{\partial^2 \vec{E}}{\partial t^2}$$

assuming that μ
and ϵ are constant
in time.

Solving Maxwell's Equations (cont'd)

Identity:

$$\vec{\nabla} \times [\vec{\nabla} \times \vec{f}] \equiv \vec{\nabla}(\vec{\nabla} \cdot \vec{f}) - \nabla^2 \vec{f}$$

Using the identity, $\vec{\nabla} \times [\vec{\nabla} \times \vec{E}] = -\mu\epsilon \frac{\partial^2 \vec{E}}{\partial t^2}$

becomes: $\vec{\nabla}(\vec{\nabla} \cdot \vec{E}) - \nabla^2 \vec{E} = -\mu\epsilon \frac{\partial^2 \vec{E}}{\partial t^2}$

Assuming zero charge density (free space; Equation 1):

$$\vec{\nabla} \cdot \vec{E} = 0$$

and we're left with: $\nabla^2 \vec{E} = \mu\epsilon \frac{\partial^2 \vec{E}}{\partial t^2}$

Solving Maxwell's Equations (cont'd)

$$\nabla^2 \vec{E} = \mu\epsilon \frac{\partial^2 \vec{E}}{\partial t^2} \quad \nabla^2 \vec{B} = \mu\epsilon \frac{\partial^2 \vec{B}}{\partial t^2}$$

The same result is obtained for the magnetic field B.

These are forms of the **3D wave equation**, describing the propagation of a sinusoidal wave:

$$\nabla^2 u = \frac{1}{v^2} \frac{\partial^2 u}{\partial t^2}$$

Where v is a constant equal to the propagation speed of the wave

So for EM waves, $v = \frac{1}{\sqrt{\mu\epsilon}}$

Solving Maxwell's Equations (cont'd)

So for EM waves, $v = \frac{1}{\sqrt{\mu\epsilon}}$,

Units of $\mu = \text{T}\cdot\text{m}/\text{A}$

The Tesla (T) can be written as $\text{kg A}^{-1} \text{s}^{-2}$

So units of μ are **$\text{kg m A}^{-2} \text{s}^{-2}$**

Units of $\epsilon = \text{Farad m}^{-1}$ or **$\text{A}^2 \text{s}^4 \text{kg}^{-1} \text{m}^{-3}$** in SI base units

So units of $\mu\epsilon$ are $\text{m}^{-2} \text{s}^2$

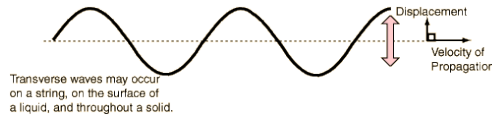
Square root is $\text{m}^{-1} \text{s}$, reciprocal is m s^{-1} (i.e., velocity)

$\epsilon_0 = 8.854188 \times 10^{-12}$ and $\mu_0 = 1.2566371 \times 10^{-6}$

Evaluating the expression gives $2.998 \times 10^8 \text{ m s}^{-1}$

Maxwell (1865) recognized this as the (known) **speed of light** – confirming that **light was in fact an EM wave**.

Why light waves are transverse



Suppose a wave propagates in the x -direction. Then it's a function of x and t (and not y or z), so all y - and z -derivatives are zero:

$$\frac{\partial E_y}{\partial y} = \frac{\partial E_z}{\partial z} = \frac{\partial B_y}{\partial y} = \frac{\partial B_z}{\partial z} = 0$$

In a charge-free medium,

$$\vec{\nabla} \cdot \vec{E} = 0 \quad \text{and} \quad \vec{\nabla} \cdot \vec{B} = 0$$

that is,

$$\frac{\partial E_x}{\partial x} + \cancel{\frac{\partial E_y}{\partial y}} + \cancel{\frac{\partial E_z}{\partial z}} = 0 \quad \frac{\partial B_x}{\partial x} + \cancel{\frac{\partial B_y}{\partial y}} + \cancel{\frac{\partial B_z}{\partial z}} = 0$$

Substituting the zero values, we have:

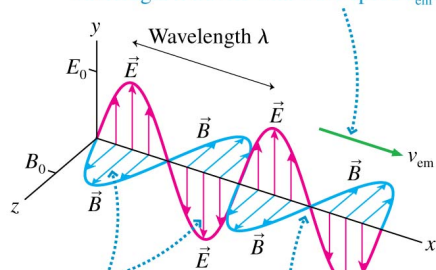
$$\frac{\partial E_x}{\partial x} = 0 \quad \text{and} \quad \frac{\partial B_x}{\partial x} = 0$$

So the longitudinal fields (parallel to propagation direction) are at most **constant**, and not waves.

The propagation direction of a light wave

FIGURE 35.19 A sinusoidal electromagnetic wave.

1. A sinusoidal wave with frequency f and wavelength λ travels with wave speed v_{em} .



2. \vec{E} and \vec{B} are perpendicular to each other and to the direction of travel. The fields have amplitudes E_0 and B_0 .
3. \vec{E} and \vec{B} are in phase. That is, they have matching crests, troughs, and zeros.

$$\vec{v} = \vec{E} \times \vec{B}$$

Right-hand screw rule

EM waves carry energy – how much?

e.g., from the Sun to the vinyl seat cover in your parked car....

The energy flow of an electromagnetic wave is described by the **Poynting vector**:

$$\vec{S} \equiv \frac{1}{\mu_0} \vec{E} \times \vec{B}$$

The intensity (I) of a time-harmonic electromagnetic wave whose electric field amplitude is E_0 , measured normal to the direction of propagation, is the average over one complete cycle of the wave:

$$I = \frac{P}{A} = S_{\text{avg}} = \frac{1}{2c\mu_0} E_0^2 = \frac{c\epsilon_0}{2} E_0^2 \quad \text{WATTS/M}^2$$

P = Power; A = Area; c = speed of light

Key point: intensity is proportional to the *square* of the amplitude of the EM wave

NB. Intensity = Flux density (F) = Irradiance (incident) = Radiant Exitance (emerging)

Electric field of a laser pointer

HE-NEON POWER 1 mWatt, diameter 1 mm². How big is the electric field near the aperture (E_0)?

$$I = \frac{P}{A} = S_{\text{avg}} = \frac{1}{2c\mu_0} E_0^2 = \frac{c\epsilon_0}{2} E_0^2 \quad A = \pi r^2 = \pi(5 \times 10^{-4})^2 \text{ m}^2$$

$$E_0 = \sqrt{\frac{2I}{c\epsilon_0}} = \sqrt{\frac{2(1270 \text{ W/m}^2)}{(3.00 \times 10^8 \text{ m/s})(8.85 \times 10^{-12} \text{ C}^2/\text{Nm}^2)}} \\ = 980 \text{ V/m}$$

Radiation Pressure

Radiation also exerts pressure. It's interesting to consider the force of an electromagnetic wave exerted on an object per unit area, which is called the **radiation pressure** p_{rad} . The radiation pressure on an object that absorbs all the light is:

$$F = P/c$$

$$p_{\text{rad}} = \frac{F}{A} = \frac{P/A}{c} = \frac{I}{c} \quad \text{Units: N/m}^2$$

where I is the intensity of the light wave, P is power, and c is the speed of light.

$$1 \text{ Watt m}^{-2} = 1 \text{ J s}^{-1} \text{ m}^{-2} = 1 \text{ N.m s}^{-1} \text{ m}^{-2} = 1 \text{ N s}^{-1} \text{ m}^{-1}$$

Solar sailing

A low-cost way of sending spacecraft to other planets would be to use the radiation pressure on a solar sail. The intensity of the sun's electromagnetic radiation at distances near the earth's orbit is about 1300 W/m^2 . What size sail would be needed to accelerate a $10,000 \text{ kg}$ spacecraft toward Mars at 0.010 m/s^2 ?

$$a = F / M = p_{\text{Rad}} A / M$$

$$p_{\text{Rad}} = I / c$$

$$A = Mac / I$$

$$A = 10^4 \times .01 \times 3 \times 10^8 / 1300 = 23 \text{ km}^2$$

About 4.8 km per side if square

Summary

- Maxwell unified existing laws of electricity and magnetism
- Revealed self-sustaining properties of magnetic and electric fields
- Solution of Maxwell's equations is the three-dimensional wave equation for a wave traveling at the speed of light
- Proved that light is an electromagnetic wave
- EM waves carry energy through empty space and *all remote sensing techniques exploit the modulation of this energy*
- <http://www.phy.ntnu.edu.tw/ntnujava/index.php?topic=35>